

HKU SPACE Community College
CCIT4064 Microcontrollers (MCU)
Assignment 2

Name: _____ SID: _____ CL _____

Total Mark: _____ / **40**

Remark: Unless otherwise specified, all questions should assume the Intel MCS-51 instruction set for assembly language questions and the Arduino Sketch (C/C++-based language) for high-level language or Arduino-related questions.

Section A – Multiple Choice (10 Marks) (1 Mark Each)

1. What is the result in the accumulator after the following instructions are executed?

MOV A, #55H
AND A, #0FH

- A) 05H
- B) 55H
- C) 50H
- D) Invalid code

2. A classic 8051 has 4 KB internal program memory and is connected to an external 64 KB ROM. The firmware image is 6 KB. Assume the external ROM is correctly decoded for the full 64 KB program space. Which statement is correct?

- A) With $\overline{EA} = \text{HIGH}$, the CPU fetches all 6 KB from internal ROM; with $EA = \text{LOW}$, it uses internal up to FFF_H and external above that.
- B) With $\overline{EA} = \text{HIGH}$, the CPU fetches the first 4 KB from internal ROM and the remaining 2 KB from external; with $EA = \text{LOW}$, the CPU fetches all 6 KB from external.
- C) With $EA = \text{HIGH}$, the CPU fetches everything from external; with $EA = \text{LOW}$, it fetches everything from internal.
- D) The EA pin only affects external data memory; program fetch is unaffected.

3. Will this code segment be executed continuously?

LOOP: MOV R0, #01H
DJNZ R0, LOOP

- A) Yes
- B) No
- C) It depends on the Carry bit.
- D) Invalid code

4. Which of the following is directly interpreted and executed by the CPU hardware without translation?

- A) C language
- B) Assembly language
- C) Machine code
- D) Java

5. Which of the following instructions uses indirect addressing mode in MCS-51?

- A) **MOV A, 30H**
- B) **MOV A, #30H**
- C) **MOV A, @R1**
- D) **MOV A, R1**

6. Find the number of machine cycles the following loop will be executed:

```

BACK:      MOV    R6, #200
           MOV    R5, #200
HERE:      DJNZ   R5, HERE
           DJNZ   R6, BACK
           END
    
```

- A) ~20000
- B) ~40000
- C) ~80000
- D) Infinite

7. Based on the principles of flame detection discussed in the article written by Winsen Electronics (<https://www.winsen-sensor.com/knowledge/principle-of-flame-detection.html>), which of the following BEST explains why a simple broadband IR phototransistor such as YG1006 (used in Lab03) is rarely used alone in professional industrial flame detection systems?

- I Industrial detectors often rely on narrow-band spectral discrimination to target specific combustion emission signatures.
- II Reliable flame detection frequently requires temporal pattern analysis to distinguish flames from steady IR sources.
- III Multi-sensor fusion improves immunity to environmental interference.
- IV The primary limitation of YG1006 is insufficient infrared sensitivity rather than lack of spectral discrimination.

- A) I and II only
- B) I, II and III only
- C) I, II and IV only
- D) I, II, III and IV

8. According to the Arduino UNO Q (2GB) reference design, which LPDDR4 memory device is used on the board?

Hint: Students should use the Arduino UNO Q hardware documentation page as a starting point:
<https://docs.arduino.cc/hardware/uno-q/>

- A) Model: IME8G32L4HA; Package: 200-ball FBGA
- B) Model: MT53E512M32D1; Package: 200-ball TFBGA
- C) Model: MT53E512M64D2; Package: 376-ball WFBGA
- D) Model: H9HCNNN8KUM; Package: 200-ball FBGA

9. Given firmware written in MCS-51 Assembly Language, which of the following microcontroller setups will execute the code the fastest?

- A) Intel 8051 MCU running at 12.0000 MHz (12 clocks per machine cycle)
- B) Company B's 8051-variant MCU running at 6.0000 MHz (6 clock per machine cycle)
- C) Company C's 8051-variant MCU running at 8.0000 MHz (4 clock per machine cycle)
- D) Company D's 8051-variant MCU running at 24.0000 MHz (1 clock per machine cycle)

10. Which ports on the Intel 8051 act as the 16-bit address lines for transferring data through it?

- A) P0 and P1
- B) P1 and P2
- C) P2 and P3
- D) None of the above

A1	A2	A3	A4	A5
A6	A7	A8	A9	A10

Section B (Short Question) (Total 30 Marks) (Answer the questions in the space provided below)

1) The original Intel MCS-51 microcontroller architecture was designed in the 1980s. In past decades, many modern derivatives of the 8051 architectures were built; this question investigates part of the many improvements and benefits of the modern technologies integrated into them.

- (a) Identify the instruction(s) that take the longest execution time on a traditional MCS-51 (8051). How many clock cycles (oscillator periods) do they take?

(1 Mark)

- (b) If a traditional MCS-51 variant runs at 30 MHz, how long does it take to execute that instruction?

(2 Marks)

- (c) With reference to the Silicon Laboratories modern MCS-51 variant, the EFM8UB1 (see the EFM8UB1 Reference Manual: <https://www.silabs.com/documents/public/reference-manuals/efm8ub1-rm.pdf>), which is based on the CIP-51 core, a fully software-compatible enhanced implementation of the standard MCS-51 instruction set, determine the clock cycles required to execute the same instruction(s) identified in Part (a), assuming the Prefetch ON configuration.

(1 Mark)

- (d) If the EFM8UB1 runs at 30 MHz, how long does it take to execute that instruction?

(2 Marks)

- (e) At the same frequency (30 MHz), what is the **minimum** performance improvement factor (how many times faster) for EFM8UB1 vs traditional MCS-51?

(1 Mark)

- 2) Write an 8051 assembly language program to perform the following operations. (The **ORG** and **END** directives are optional.)
- (a) Load the accumulator (**A**) with the value 80_H.
 - (b) Load register **R0** with the value 64_H. (Label this instruction as “**Q1Lable**”.)
 - (c) Multiply the accumulator by 128. (Hint: The multiplication result is stored as: the high byte in register B and the low byte in accumulator A.)
 - (d) Add the contents of **R0** to the accumulator.
 - (e) Move the content of the accumulator (**A**) to the low-byte of **DPTR**.
 - (f) Move the content of register **B** to the high-byte of **DPTR**.

Note: The complete program (including starting and ending directives) should be within 10 lines.
Remark: The program must use only native Intel MCS-51 instructions. Do not use macros, pseudo-instructions, or IDE/assembler shortcuts that expand into multiple instructions. To avoid assembler symbol assumptions, write all SFR accesses (except A/ACC) using direct addresses.

(4 Marks)

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- 3) Following Question B2, what is the address indicated by DPTR?

(2 Marks)

- 4) By default, the Intel MCS-51 instruction set does not provide an **ADD B, Rn** instruction. You are required to perform the equivalent operation in 8051 assembly. Write a subroutine named ADDB that performs the following:
- Adds the value in register R0 to register B, and stores the result back in B (i.e., $B \leftarrow B + R0$).
 - Preserves the original contents of A (ACC) and the PSW register.
 - The subroutine must start at address 0100H.
 - Write brief comments for each instruction to explain your approach.

Assume that the first two bytes of general-purpose internal RAM, 30H and 31H, are available for temporary storage.

Note: The complete subroutine (including starting/ending directives) must be within 10 lines.

Remark: Assembler symbols (e.g., A, B, PSW) may be used.

(5 Marks)

[illegible]

- 5) Calculate the results (both binary and hexadecimal values) with the calculation step and show the status of CY, AC, and P flags after the addition of (AA)₁₆ and (88)₁₆ of the following instructions.

MOV A, #AAH

ADD A, #88H

(4 Marks)

[illegible]

6) You are required to use an Arduino UNO R3 to control the brightness of an LED using a potentiometer as the analog input.

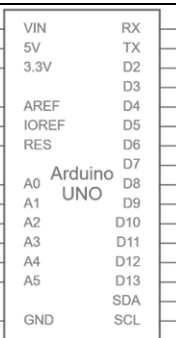
(a) Draw a simplified schematic diagram and clearly indicate the wiring connections among the following components:

- Arduino UNO R3
- 1 × LED
- 1 × potentiometer
- 1 × current-limiting resistor

Your circuit must be able to:

- Read an analog voltage from the potentiometer using an Arduino analog input pin.
- Convert the measured analog input level into an appropriate output control signal for adjusting LED brightness.

Remark: For simplicity, you may ignore pins that are not used in your design (e.g., AREF).

		
1 x Resistor	1 x Potentiometer	1 x LED
 1 x Arduino UNO R3		
Table 1: Component List for Question 6		

(3 Marks)

(b) Write a **complete Arduino sketch** that implements the circuit in (a). Your program must achieve all of the following:

- Analog Input Reading and Level Conversion
 - Read the potentiometer value using `analogRead()` (range: 0 to 1023).
 - Convert the analog input into **five discrete levels: 0, 1, 2, 3, 4**, according to the following ranges:

Analog Input Range	Level
0 – 200	0
201 – 400	1
401 – 600	2
601 – 800	3
801 – 1023	4

- Serial Monitor Output
 - Print the analog input value and its level to the Serial Monitor in the following format:

Analog Input: <value>; Level: <level>
(Example: Analog Input: 356; Level: 1)

- LED Brightness Control
 - Control the LED brightness based on the converted level.
 - Convert the analog input into **five discrete levels: 0, 1, 2, 3, 4**, according to the following ranges:
 - **0** → LED **OFF**; **1** → LED at **1/4 intensity**; **2** → LED at **half intensity**; **3** → LED at **3/4 intensity**; **4** → LED at **full intensity**

(5 Marks)

Important remarks:

- Answer all questions in the space provided.
- Submit your assessment via SOUL. **Do NOT compress your files.**
- Submission should include the following file:
 - CCIT4064_A2_YourName_SID.pdf (convert your completed answer book to PDF format)
- Penalties will apply in (but are not limited to) the following cases:
 - Assignment submitted after the grace period.
 - Assignment submitted with an incorrect file format or file name.
 - Missing or incorrect student information in the assignment.
- This is an INDIVIDUAL assessment. Plagiarism or collusion, once verified, will result in mark penalties and an unofficial record.

- End of Assignment 2 -